# Process and Thread Management

"Ausgewählte Betriebssysteme" Professur Betriebssysteme Fakultät Informatik

#### Outline

- · Data Structures
- · Process Creation
- · Thread Creation
- Scheduling

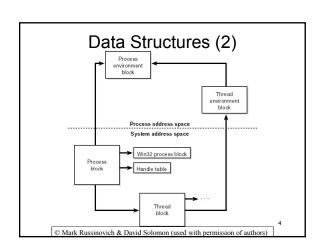
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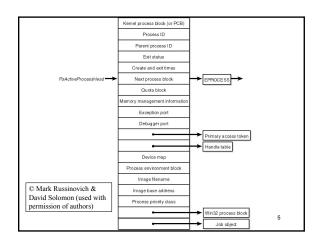
2

#### **Data Structures**

- Process represented by EPROCESS (executive process) block
- Thread represented by ETHREAD block
- · One process contains at least one thread
- EPROCESS and ETHREAD plus associated structures exist in system address space
- Process and thread environment blocks (PEB, TEB) exist in user address space

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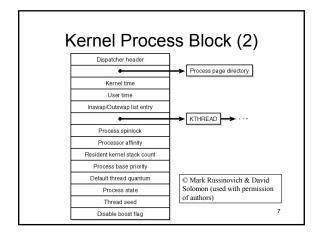




## Kernel Process Block (PCB)

- Contains basic information needed to manage processes and their threads
  - Page directory
  - Kernel thread block list
  - State
  - Etc.

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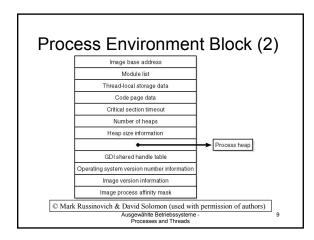


#### **Process Environment Block**

- · Contains information for:
  - Image loader
  - Heap manager
  - Other Win32 system DLLs
- Always mapped at 0x7ffdf00

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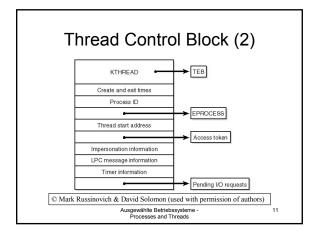
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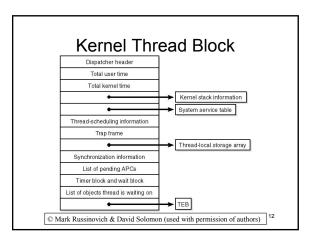


#### Thread Control Block

- · Kernel object used to schedule threads
- Win32 subsystem maintains parallel structure for each Win32 thread
- Kernel-mode portion of Win32 subsystem maintains parallel structure for thread using GUI or USER functions
- · Fibers:
  - Managed in user-mode by Win32 subsystem
  - First fiber created from thread
  - Successive fiber created explicitly
  - Executed if called through SwitchToFiber

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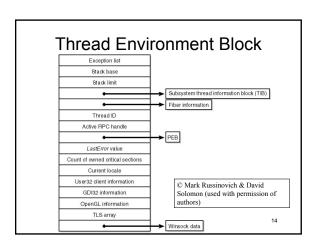


## Kernel Thread Block (2)

- Dispatcher header: thread can be waited on, need dispatcher object
- System service dispatch table (see Introduction – 20)
- Scheduling information: base priority, current priority, quantum, affinity mask, ...
- Pending APCs (see Interrupts 17)

• ...

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Stage 1

Stage 1

Create
Stage 2

Stage 3

Windows 2000
Orrocas object
Create
Windows 2000
Windo

#### Create a Process

- 1. Open image file
- 2. Create EPROCESS object
- 3. Create initial thread (stack, context, ETHREAD)
- 4. Notify Win32 subsystem (set up for new process and thread)
- 5. Start execution of initial thread (unless CREATE\_SUSPENDED)
- 6. In context of new process and thread:
  - · Complete initialization of address space (load DLLs, ...)
  - Begin execution of program

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### Assign Priority to Process

- Can specify more than one priority class in Create Process call → lowest used
- If no priority class specified Normal is used, unless priority class of parent is Idle or Below Normal
- If Real-time is specified and parent doesn't have Increase Scheduling Priority privilege High is used

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# Opening an Image (stage 1)

- If image is OS/2 application, image changes to os2.exe and restart
- · If image is MS-DOS application
  - Check for running Virtual Dos Machine (VDM)
  - If exists, use it to run application
  - If not, image is changed to  $\mathtt{ntvdm.exe}$  an restart
- If image has .bat or .cmd extension image changed to cmd.exe and restart
- If image is Win16, decide if has to create new VDM (flags of Create Process call)

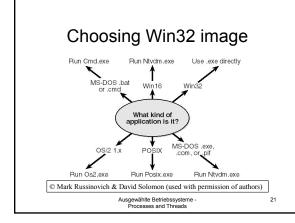
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19

## Opening an Image (2)

- Now valid Win2K exe is opened and a section object exists for it (not mapped yet)
- If image is Posix, image changes to Posix.exe and restart
- If image is DLL Create Process fails
- Now check registry for entry (if exists use specified image and restart) – see example

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## Create EPROCESS Object

- Set up EPROCESS block (quota, process ID, access token)
- · Creating initial process address space
  - Create three initial pages for page directory, hyperspace page, working set list
  - Page table pages for non-paged system space and system cache are mapped into process
- Initialize kernel process block (pointers)

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# Create EPROCESS Object (2)

- · Conclude address space setup
  - VM manager initializes internal data structures
  - Ntdll.dll mapped
- · Set up PEB
  - Image base address, heap variables, version numbers, ...
- · Complete Setup
  - Initialize handle table
  - Set flags from image file in PEB

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23

## Notify Win32 Subsystem

- · Duplicate handles for process and thread
- · Set priority class
- · Csrss process block is allocated
- Exception port is set to Win32 subsystem's exception port
- · Debug port is set to subsystem's debug port
- Csrss thread block allocated and initialized and queued in process thread list
- · Subsytem internal counters incremented

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#### Initialize in Context of Process

- Initialize loader, heap manager, critical section structures, ...
- · Load required DLLs
- If debugged, suspend all threads and attach to debugger (via debug port)
- · Start execution

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#### Create a Thread

- 1. Create user-mode stack
- 2. Initialize thread's hardware context
- Create executive object (kernel) and initialize it (access token, ID, kernel stack, priority, ...)
- 4. Win32 subsystem is informed about thread
- 5. Thread handle and ID returned to caller
- When running finish initialization: register with DLLs and debugger, etc.

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27

# Create Thread (2)

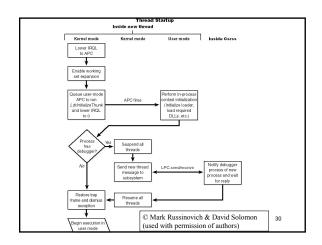
- to 3.:
  - Thread count in process is incremented
  - Executive thread block created (ETHREAD)
  - Thread ID created
  - Thread's kernel stack allocated
  - TEB is set up in user-mode address space
  - Thread start address stored on kernel stack
  - Set up KTHREAD block (priority, affinity, quantum, machine-dependant hardware context (trap, exception frames, ...), ...)
  - Thread access token set to process' access token

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## Create Thread (3)

- to 6.:
  - lower IRQL to APC → system init thread routine fires
  - enable working set expansion and start loader initialization
  - call loaded DLLs to notify of new thread
  - If debugger is attached suspend all threads and call debugger
  - main thread begins execution in user mode (use trap, which has been initialized earlier)

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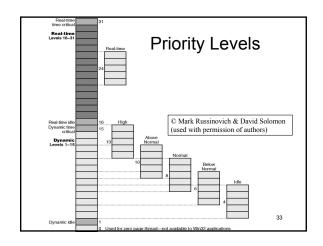
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31

## **Thread Scheduling**

- · Priority driven and preemptive Scheduling
- Runs for amount of time called quantum
- Can be restricted to subset of processors (processor affinity)
- "Scheduler" spread throughout kernel (scheduling code called dispatcher)
- Dispatching occurs at DPC/dispatch level
- Dispatching triggered by:
  - Thread becomes ready (create, return from wait)
  - Thread leaves running state (terminate, quantum end, ...)
  - Thread's priority changes
  - Processor affinity of running thread changes

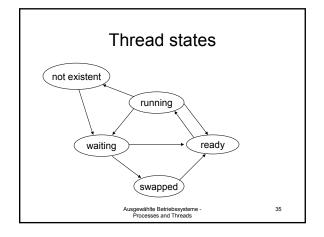
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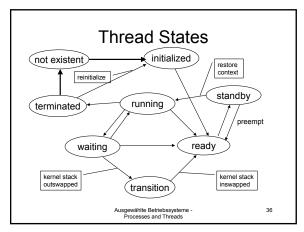


# Priority Levels (2)

- Thread priority is based on priority class and relative priority (called base and current priority)
- Some system processes have priority slightly higher than Normal (default)
- Real-time thread never have priority changed (kernel mode system threads use this range)
- Real-time threads have their quantum reset when preempted
- Kernel-mode threads may raise IRQL to 1 (APC)
- On multi-processor system spin lock used for synchronization of dispatcher data

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#### Quantum

- Thread starts with quantum of 6 (Professional) or 36 (Server)
- On each clock interrupt 3 is subtracted from quantum (if 0 another thread is scheduled)
- Even if not running (IRQL >= DPC level) quantum is reduced (wait)
- Threads at priority < 14 and wait have quantum reduced by 1 when returning from wait
- Threads at priority >= 14 and wait have quantum reset when returning from wait
- Clock interrupt on single-processor x86 about 10ms (multi-processor x86 15ms)

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#### Quantum boost

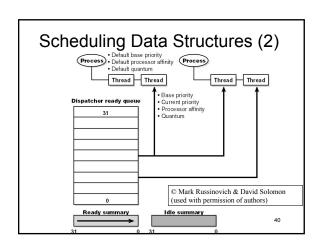
- Foreground window's threads have quantum boosted
- Better than priority boost, because background processes still run
- Value determined by registry; can vary between 6 to 36

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# Scheduling Data Structures

- · Dispatcher database:
  - Which threads are waiting
  - Which threads are running
  - Which processes are executing which threads
- · Dispatcher ready queue:
  - One queue per priority
  - Bit mask, which priority has ready threads
- · Idle summary:
  - Which processor is idle

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## **Scheduling Scenarios**

- · Voluntary Switch:
  - Wait for object (semaphore, event, I/O completion, ...)
  - Thread goes to wait queue
- Preemption
  - Higher priority thread's wait completes
  - Thread priority is changed
  - Running thread is put at head of it's priorities ready queue
- Quantum end
  - Thread moves to tail of ready queue
- Termination

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## **Priority Boost**

- · Can boost priority in five cases:
  - On I/O completion (boost defined by driver)
  - After waiting on events or semaphores (boosted by 1)
  - After foreground thread completes wait
  - When GUI threads wake up (boosted by 2)
  - When ready thread hasn't run for some time (ready and not run for > 300 clock intervals ~3-4 seconds; boosted to 15 + double quantum)

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